

Richardson-Lucy Algorithm for image restoration

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This document explains Richardson-Lucy algorithm Lucy [1974]; Richardson [1972] which is used for image restoration.

1 Imaging equation

Assuming Poisson noise, imaging equation is derived as

$$g(x) = \text{Poisson}(f(x) \otimes h(x)), \quad (1)$$

where g , f , and h are a blurred image, the latent image, and the Point Spread Function (PSF) respectively. *Poisson* operator adds Poisson noise to the image.

2 Bayes' theorem

Given a blurred image g , a posterior distribution is

$$P(f(x)|g(x)) = \frac{P(g(x)|f(x))P(f(x))}{P(g(x))}, \quad (2)$$

where $P(g(x)|f(x))$, $P(g(x))$, and $P(f(x))$ are the likelihood, the evidence, and the prior distribution.

3 Poisson noise likelihood

When image noise follows Poisson distribution, the likelihood is formulated as

$$P(g(x)|f(x)) = \prod_x \frac{f(x) \otimes h(x)^{g(x)} \exp(-f(x) \otimes h(x))}{g(x)!}. \quad (3)$$

Maximization of the likelihood is equivalent to minimization of its negative logarithm. Therefore, the negative

log likelihood $L(f(x))$ is

$$L(f(x)) = -\ln(P(g(x)|f(x))) \quad (4)$$

$$= \sum_x \ln \frac{f(x) \otimes h(x)^{g(x)} \exp(-f(x) \otimes h(x))}{g(x)!} \quad (5)$$

$$= \sum_x f(x) \otimes h(x) - g(x) \ln(f(x) \otimes h(x)) + \ln g(x)!. \quad (6)$$

Consider a small perturbation Δx . The negative log likelihood $L(f(x + \Delta x))$ is

$$L(f(x + \Delta x)) = \sum_x f(x + \Delta x) \otimes h(x) - g(x) \ln(f(x + \Delta x) \otimes h(x)) + \ln g(x)!. \quad (7)$$

Removing constant term w.r.t. f , we obtain

$$L(f(x + \Delta x)) = \sum_x f(x + \Delta x) \otimes h(x) - g(x) \ln(f(x + \Delta x) \otimes h(x)). \quad (8)$$

Assuming $f(x + \Delta x) = f(x) + f(\Delta x)$,

$$\begin{aligned} L(f(x + \Delta x)) &= \sum_x (f(x) + f(\Delta x)) \otimes h(x) - g(x) \ln((f(x) + f(\Delta x)) \otimes h(x)) \\ &= \sum_x f \otimes h(x) + f \otimes h(\Delta x) - g(x) \ln(f \otimes h(x) + f \otimes h(\Delta x)). \end{aligned} \quad (9)$$

For simplicity,

$$\begin{aligned} f \otimes h(x) &= f(x) \otimes h(x), \\ f \otimes h(\Delta x) &= f(\Delta x) \otimes h(x). \end{aligned}$$

$$\begin{aligned} L(f(x + \Delta x)) &= \sum_x f \otimes h(x) + f \otimes h(\Delta x) - g(x) \ln(f \otimes h(x) + f \otimes h(\Delta x)) \\ &= \sum_x f \otimes h(x) + f \otimes h(\Delta x) - g(x) \ln \left[f \otimes h(x) \left(1 + \frac{f \otimes h(\Delta x)}{f \otimes h(x)} \right) \right] \\ &= \sum_x f \otimes h(x) + f \otimes h(\Delta x) - g(x) \ln(f \otimes h(x)) - g(x) \ln \left(1 + \frac{f \otimes h(\Delta x)}{f \otimes h(x)} \right) \\ &= L(f(x)) + \sum_x f \otimes h(\Delta x) - g(x) \ln \left(1 + \frac{f \otimes h(\Delta x)}{f \otimes h(x)} \right). \end{aligned}$$

Following Taylor expansion $\ln(1 + x) \approx x - \frac{x^2}{2}$,

$$\begin{aligned} L(f(x + \Delta x)) &= L(f(x)) + \sum_x f \otimes h(\Delta x) - g(x) \ln \left(1 + \frac{f \otimes h(\Delta x)}{f \otimes h(x)} \right) \\ &= L(f(x)) + \sum_x f \otimes h(\Delta x) - g(x) \frac{f \otimes h(\Delta x)}{f \otimes h(x)} + \frac{1}{2} g(x) \left(\frac{f \otimes h(\Delta x)}{f \otimes h(x)} \right)^2. \end{aligned}$$

Omitting the last term, because it's too small,

$$\begin{aligned} L(f(x + \Delta x)) &= L(f(x)) + \sum_x f \otimes h(\Delta x) - g(x) \frac{f \otimes h(\Delta x)}{f \otimes h(x)} \\ &= L(f(x)) + \sum_x f \otimes h(\Delta x) \left(1 - \frac{g(x)}{f \otimes h(x)}\right). \end{aligned}$$

From the definition of convolution integral $\int ab \otimes cd x = \int ba \otimes \bar{h} dx$, where $\bar{h}h$ is the adjoint of h ,

$$\begin{aligned} L(f(x + \Delta x)) &= L(f(x)) + \sum_x f \otimes h(\Delta x) \left(1 - \frac{g(x)}{f \otimes h(x)}\right) \\ &= L(f(x)) + \sum_x f \left(1 - \frac{g(x)}{f \otimes h(x)}\right) \otimes \bar{h}(\Delta x). \end{aligned}$$

The partial derivative of $L(f(x))$ on x is derived as

$$\begin{aligned} \frac{\partial L(f(x))}{\partial x} &= \frac{L(f(x + \Delta x)) - L(f(x))}{\Delta x} \\ &= \frac{1}{\Delta x} \sum_x f \left(1 - \frac{g(x)}{f \otimes h(x)}\right) \otimes \bar{h}. \end{aligned}$$

Since the minimization of the negative log likelihood is obtained by finding x satisfying

$$\frac{\partial L(f(x))}{\partial x} = 0.$$

Thus, we have

$$\begin{aligned} \left(1 - \frac{g(x)}{f \otimes h(x)}\right) \otimes \bar{h} &= 0 \\ 1 - \frac{g(x)}{f \otimes h(x)} \otimes \bar{h} &= 0 \end{aligned} \tag{10}$$

Using the convergence condition $\frac{f^{n+1}}{f^n} = 1$, we obtain the update rule as

$$\frac{f^{n+1}}{f^n} = \frac{g(x)}{f \otimes h(x)} \otimes \bar{h}. \tag{11}$$

Finally, we obtain the Richardson-Lucy deconvolution algorithm as

$$f^{n+1} = \left(\frac{g(x)}{f \otimes h(x)} \otimes \bar{h} \right) f^n. \tag{12}$$

Bibliography

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